

CATALOG DESCRIPTION

An introduction to basic engineering structural analysis of static (stationary) objects. Methods to examine external and inter forces on structural components are developed using vector methods.

Prerequisites: PHYS 215 and MATH 189

Semester Offered: Fall



Course Learning Outcomes

Upon successful completion of the course, the student will be able to...

- 1. Forces, moments, and couples.
- 2. Mechanical systems and equilibrium.
- 3. Center of gravity, centroid, and moments of inertia.

Special Learning Outcomes

Upon successful completion of the course, the student will be able to...

- 1.1 Represent forces, moments, and couples as vectors.
- 1.2 Manipulate 2 and 3-dimensional vectors graphically and algebraically.
- 1.3 Use position vectors and unit vectors to represent direction.
- 1.4 Perform dot product and cross product vector operations.
- 1.5 Verbally define the moment of a force, and of a couple.
- 1.6 Apply the rules of movement of forces, moments, and couples on a rigid body.
- 1.7 Reduce a complex system of forces to a single force and a moment at a specified point.
- 1.8 Further reduce a system of forces to a single force, acting around a specified axis.
- 1.9 Reduce distributed loads to a single force.
- 2.1 Know and apply the conditions for rigid-body equilibrium.
- 2.2 Draw simple free-body diagrams which represent actual mechanical systems.
- 2.3 Use free-body diagrams to write the equations of equilibrium in 2 and 3-dimensions.
- 2.4 Solve the resulting simultaneous equations using matrices and a scientific calculator.
- 2.5 Apply force and moment constraints to various mechanical supports.
- 2.6 Know and apply the assumptions made in the analysis of simple trusses.
- 2.7 Define a two-force member.
- 2.8 Apply engineering judgment to simple truss structures in order to determine whether the members are in compression or tension.
- 2.9 Draw free-body diagrams and analyze trusses using the methods of joints and sections.
- 2.10 Apply analysis methods to simple frames and machines.
- 2.11 Describe how external forces and moments on structural members translate into internal forces and moments.
- 2.12 Relate internal forces to the process of structural member design.
- 2.13 Calculate internal forces at specific structural locations.
- 2.14 Calculate frictional forces and apply them to structural analysis.
- 3.1 Define and calculate the center of gravity position for a system of particles.
- 3.2 Differentiate between the concepts of center of gravity and center of mass.
- 3.3 Explain the calculus-based derivation of center of gravity, center of mass, and centroid for a randomly shaped solid body.
- 3.4 Use calculus based arguments to calculate center of gravity, center of mass, and centroid for simple, symmetrical objects.
- 3.5 Verbally define the concepts of area and mass moments of inertia.
- 3.6 Explain the calculus-based derivation of moment of inertia.
- 3.7 Relate the relevance of moment of inertia to design of structural members.
- 3.8 Calculate moments of inertia for various single piece and composite physical cross sections.